# SpaceLogic MP130-24T/-230T

Motoric Actuators for Two Position Control For VP228E/VP229E PIBCV, DN10...32



# **Product Description**

MP130-24T and MP130-230T are 2-point three-wire actuators used with **SpaceLogic** PIBCV DN 10...32 valves. The actuator can be used with fan coil units, induction units, small reheaters, recoolers and zone applications in which hot/cold water is the controlled medium. The actuator default factory setting is for the spindle to be fully retracted which equates to a normally open function.

The setting between normally closed and normally open is configured with jumper connections (see "Wiring and connections" for jumper settings).

## Specifications

Part Numbers	
24 Vac	MP130-24T
230 Vac	MP130-230T
Power supply	24 Vac, 230 Vac; +1015%
Power consumption	1 VA - 24 Vac; 8 VA - 230 Vac
Frequency	50/60 Hz
Close off force	200 N
Stroke	5.5 mm
Speed	12 s/mm
Max. medium temperature	130 °C
inside the pipe	
Ambient temperature	0 55 °C
Storage and transport temp.	_40 +70 °C
Protection code	IP 42
Weight	0.3 kg
Sound Power Level	Max. 35 dB(A)
EMC Directive	2014/30/EU
& Standards	EN 61000-6-2 & EN 61000-6-3
LVD Directive	2014/35/EU
& Standards	EN 60730-1 & EN 60730-2-14
RoHS2 Directives	2011/65/EU &
	RoHS2 Amendment 2015/863/EU

#### Features

- 2 point three-wire actuator
- Automatic switch-off upon valve closure prevents overload
  of actuator and valve
- No tools required for mounting
- Maintenance-free lifetime
- Low-noise operation
- Supplied with 1.5 m cable

#### **Dimensions (mm)**





MP130 installs to **SpaceLogic** PIBCV 10mm... 32mm valves (VP228E and VP229E)



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# Mounting and Installation

The actuator should be mounted with the valve stem in either horizontal position or pointing upwards. The actuator is fixed to the valve body by means of a mounting ring, which requires no tools for mounting. The ring should be tightened by hand.



# Wiring and Connections

NOTE: It is strongly recommended that the mechanical installation is completed before the electrical installation. Each actuator is supplied with the connecting cable for the controller. NOTE: Do not touch anything on the PCB. Do not remove the cover before the power supply is fully switched off.

- 1. Check the valve neck. The actuator should be in stem up position (factory setting). Ensure that the actuator is mounted securely on the valve body.
- 2. Wire the actuator according to the wiring diagram.
- 3. Stem movement is indicated by the Position Indicator (a small pin riding in a channel as shown in (1) above).



Jumper setting

sw=OFF actuator retracted (opens valve) sw=ON actuator extracted (closes valve)

(closes valve) sw=ON actuator retracted (opens valve) default setting for use with PIBCV valve

# Manual Override

- Remove cover (1) inserting flat screwdrivers heads into 1. the slots and pry off the cover with an upward mortion.
- Press and hold the button (2) on the bottom side of the 2. actuator during manual override (3) twisting of knob.
- 3. Replace cover and install actuator on valve.

NOTE: A "click" sound after energising the actuator means that the gear wheel has jumped into normal position.



### ΝΟΤΙ

#### **RISK OF EQUIPMENT DAMAGE**

- · Avoid electrical noise interference.
- · Do not install near large contactors, electrical machinery, or welding equipment.
- Only use manual override when power is off.

Failure to follow these instructions may result in damage to the gear train or other mechanical damage.



#### Jumper setting

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sw=OFF actuator extracted (closes valve) sw=ON actuator retracted (opens valve) default setting for use with PIBCV valve

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